Precipitation and Temperature Forecast Performance at the Weather Prediction Center

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ABSTRACT

The role of the human forecaster in improving upon the accuracy of numerical weather prediction is explored using multiyear verification of human-generated short-range precipitation forecasts and mediumrange maximum temperature forecasts from the Weather Prediction Center (WPC). Results show that human-generated forecasts improve over raw deterministic model guidance. Over the past two decades, WPC human forecasters achieved a 20%-40% improvement over the North American Mesoscale (NAM) model and the Global Forecast System (GFS) for the 1 in. (25.4 mm) (24 h)⁻¹ threshold for day 1 precipitation forecasts, with a smaller, but statistically significant, 5%-15% improvement over the deterministic ECMWF model. Medium-range maximum temperature forecasts also exhibit statistically significant improvement over GFS model output statistics (MOS), and the improvement has been increasing over the past 5 yr. The quality added by humans for forecasts of high-impact events varies by element and forecast projection, with generally large improvements when the forecaster makes changes \geq 8°F (4.4°C) to MOS temperatures. Human improvement over guidance for extreme rainfall events $[3 \text{ in.} (76.2 \text{ mm}) (24 \text{ h})^{-1}]$ is largest in the short-range forecast. However, human-generated forecasts failed to outperform the most skillful downscaled, biascorrected ensemble guidance for precipitation and maximum temperature available near the same time as the human-modified forecasts. Thus, as additional downscaled and bias-corrected sensible weather element guidance becomes operationally available, and with the support of near-real-time verification, forecaster training, and tools to guide forecaster interventions, a key test is whether forecasters can learn to make statistically significant improvements over the most skillful of this guidance. Such a test can inform to what degree, and just how quickly, the role of the forecaster changes.

1. Introduction

As the skill of numerical weather prediction (NWP) and associated postprocessed guidance continues to improve, recent debate asks to what degree can human forecasters add quality¹ to NWP (e.g., Mass 2003; Bosart 2003; Roebber et al. 2004; Reynolds 2003; Doswell 2004; Stuart et al. 2006, 2007; Homar et al. 2006; Novak et al.

2008; Ruth et al. 2009). The National Centers for Environmental Prediction's (NCEP) Weather Prediction Center (WPC²) has a broad mission to serve as a center of excellence in quantitative precipitation forecasting, medium-range forecasting, winter weather forecasting, surface analysis, and the interpretation of operational NWP. Historically, forecasters at the WPC have had access to a large portion of the available model guidance suite, recently including multimodel ensemble information from international partners. The WPC's unique national forecast mission coupled with its access to state-of-the-art model guidance provides a rare opportunity to assess the quality added by humans to ever-improving NWP guidance.

This work will examine multiyear historical and contemporary verification for short-range deterministic

¹Although "value added" is often used colloquially, this work abides by the terms for forecast "goodness" defined in Table 1 of Murphy (1993), where "value" refers to the benefit realized by decision makers through the use of the forecasts and "quality" refers to the correspondence between forecasts and the matching observations.

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² The center's name was changed from the Hydrometeorological Prediction Center to the Weather Prediction Center on 5 March 2013.

precipitation forecasts and medium-range maximum temperature forecasts generated at the WPC. Although humans can add substantial value to NWP through retaining forecast continuity (run-to-run consistency), assuring element consistency (e.g., wind shifts with fronts), and helping users make informed decisions (e.g., Roebber et al. 2010), this work focuses on the human role in improving forecast accuracy. In this respect, the current work examines only one component of the forecaster's role, and is limited to analysis of just two weather elements.

The current work builds upon and extends previous analyses of WPC skill by Olson et al. (1995), Reynolds (2003), and Sukovich et al. (2014, manuscript submitted to *Wea. Forecasting*, hereafter SRNBR), and points to future verification approaches in the continuing history of NWP and the human forecaster. Section 2 presents analysis of quantitative precipitation forecasts (QPFs) while section 3 explores human improvement to mediumrange maximum temperature forecasts. A discussion of the limitations of the work and implications of the verification for the future role of the forecaster is presented in section 4.

2. QPF

a. Production and verification method³

The WPC forecasters create deterministic QPFs at 6-h intervals through the day 3 forecast projection, and 48-h QPFs for days 4-5 and 6-7. The focus here is on the day 1-3 forecasts. The WPC deterministic QPF during the study period was defined as the most-likely, arealaveraged amount mapped onto a 32-km horizontal resolution grid. An example 24-h accumulated QPF is shown in Fig. 1a. The forecast process for QPF involves forecaster assessment of observations of moisture, lift, and instability, as well as comparisons among deterministic and ensemble forecasts of these parameters. Objectively postprocessed model-based QPFs are also available to WPC forecasters. Emphasis shifts from nowcasting based on observations in the first 6-12 h of the forecast, to an increasing use of NWP as lead time increases. For example, subjective blends of model guidance are used almost exclusively beyond 36 h. Forecasters manually draw precipitation isohyets, which operational software converts into a grid. In areas of complex topography, forecasters use monthly Parameterelevation Regressions on Independent Slopes Model (PRISM; Daly et al. 1994; Daly et al. 2008) output as a background.

The 24-h accumulated QPF was verified using a human quality-controlled (QCed) analysis valid at 1200 UTC. The analyst can choose a first-guess field from either the multisensor stage IV quantitative precipitation estimate mosaic analyses (Lin and Mitchell 2005) or Climate Prediction Center (CPC) daily precipitation analyses (Higgins et al. 1996). The analyst QCs the analysis based on gauge data and a review of radar data, and can adjust isohyets if necessary. The QCed precipitation analysis is mapped onto a 32-km grid, matching the forecast grid. Retrospective tests show that the relative skill difference between the WPC and NWP datasets shown in this paper are not sensitive to the precipitation analysis used (e.g., the WPC QCed analysis or stage IV).

Conventional 2×2 contingency tables of dichotomous outcomes (e.g., Brill 2009) for precipitation exceeding several thresholds are created by comparing each QPF to the corresponding verifying analysis. The 2×2 contingency tables are used to calculate the threat score and frequency bias for the day 1 and day 3 forecast periods. The WPC forecast period naming convention is shown in Fig. 2. Focus is placed on the threat score for the day 1 QPF valid at 1200 UTC at the 1 in. (25.4 mm) $(24 h)^{-1}$ threshold. This threat score is reported to Congress as part of the Government Performance and Results Act of 1993 (GPRA). Historically, the goal of the WPC QPF was to improve upon the model guidance available during the interval of forecast preparation (Reynolds 2003). Therefore, the performance of the WPC QPF is compared against model forecasts that are somewhat older (i.e., time lagged) than the WPC issuance time. The latency of the WPC forecasts for the most frequently used model guidance is shown in Table 1.

The historical verification analysis was constrained to data available during the last \sim 50 yr, which were largely deterministic forecasts. Bias-corrected forecasts were also generally not available for verification purposes during the historical time frame. Bias correction can dramatically improve raw QPF guidance (e.g., Yussouf and Stensrud 2006; Brown and Seo 2010), and ensemble approaches can quantify predictability and reduce error. Thus, the contemporary verification compares the WPC QPF to one created by an ensemble algorithm with bias correction, issued near the time of the human-modified forecast. This product, the pseudo-bias-corrected ensemble QPF (ENSBC), is based on the premise that the larger the uncertainty, the smoother the forecast should be, whereas the smaller the uncertainty, the more detailed the forecast should be. During the study period the ENSBC was composed of a high-resolution ensemble part composed of output from the deterministic NCEP North American Mesoscale (NAM) model (Janjić 2003), Global Forecast System (GFS; Caplan et al. 1997), and

³Forecast production methods are described throughout the paper as they were conducted during 2012, and may have since changed.

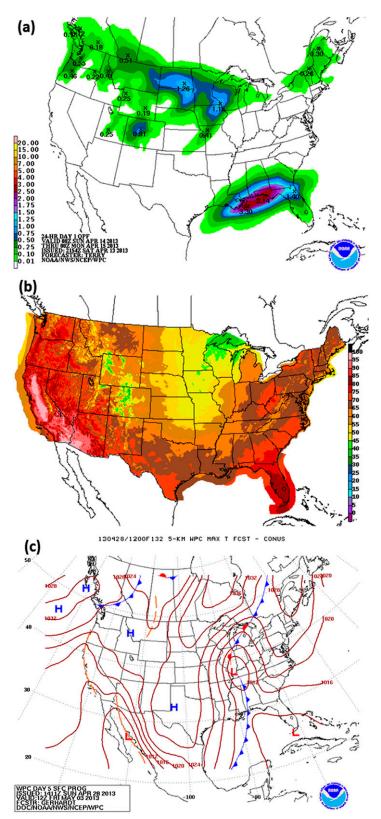


FIG. 1. Examples of WPC forecasts of (a) QPF (shaded, from 0.01 to 20.0 in.), (b) medium-range maximum temperature [shaded, °F from -5° to 105°F (from -20.6° to 40.6°C)], and (c) medium-range pressure patterns and fronts. Examples are from different days.

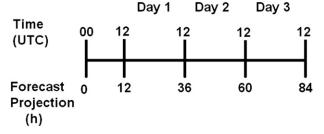


FIG. 2. Timeline showing the WPC forecast period naming convention for the overnight issuance, including the forecast projection (h), time (UTC), and day 1, day 2, and day 3 designations.

European Centre for Medium-Range Weather Forecasts (ECMWF; Magnusson and Kallen 2013), and a full ensemble part composed of the high-resolution ensemble plus the Canadian Global Environmental Multiscale Model (GEM; Bélair et al. 2009), Met Office model (UKMO), and all members of the NCEP Short-Range Ensemble Forecast (SREF; Du et al. 2006). The product is objectively downscaled from 32 to 10 km (5 km over the west) using PRISM. A detailed description of the ENSBC algorithm is provided in appendix A.

Additionally, the historical analysis is limited to verification metrics with a long record to facilitate historical context [threat score, frequency bias (referred to as bias hereafter), and mean absolute error (MAE)]. Metrics such as the threat score have inherent limitations, including a double penalty for false alarms (Baldwin et al. 2002) and bias sensitivity (Brill 2009; Brill and Mesinger 2009). To address this issue, a bias-removed threat score is calculated using the procedure based on probability matching (Ebert 2001) described by Clark et al. (2009). The procedure uses probability matching to reassign the distribution of a forecast field with that of the observed field, so that the modified forecast field has the same spatial patterns as the original forecast, but has values adjusted so the distribution of their amplitudes exactly matches those of the analysis. The end result is the removal of all bias. Because the NAM precipitation skill lags so severely relative to WPC and other international guidance, and to simplify interpretation, the biasremoved threat score calculation was not conducted for the NAM. This reduced skill is likely due to the use of 6-h-old boundary conditions from the GFS, an earlier data cutoff, as well as a less advanced data assimilation system (G. DiMego and E. Rogers 2013, personal communication).

Finally, it is important to quantify the statistical significance of comparisons. To accomplish this task, the forecast verification system (fvs) software was used (described in appendix B). Assessment of statistical significance in fvs is accomplished using random resampling following the method of Hamill (1999).

TABLE 1. Timing of the availability of day 1 QPF guidance from the WPC, GFS, NAM, and ECMWF systems. The elapsed time between when guidance is available and when the WPC forecast is available (WPC latency) is shown in the right column.

Guidance source	Time available (UTC)	WPC latency (h)
Overnight WPC	1000	
0000 UTC GFS	0500	5
0000 UTC NAM	0300	7
0000 UTC ECMWF	0700	3
Overnight ENSBC	0900	1

Thus, contemporary verification addressing these four issues (ensemble approaches, bias-corrected guidance, bias sensitivity, and statistical significance) was conducted during the latest years available (2011–12).

b. Results

Verification of the WPC QPF over the last 50 yr (Fig. 3) is a testament to the advancement of precipitation forecasts. Threat scores of the 1 in. $(24 h)^{-1}$ threshold for day 1 forecasts doubled during the period, while day 2 and 3 forecasts also continued to improve (Fig. 3). Improvement has accelerated after 1995. This improvement is directly tied to the quality of the NWP guidance. In fact, during the 1993–2012 period, the correlations of yearly values of the day 1 threat score for the 1 in. $(24 h)^{-1}$ threshold between WPC and the NAM and WPC and the GFS were 0.91 and 0.88, respectively.

Although NWP serves as skillful guidance, verification over the past two decades shows WPC human forecasters achieved a 20%–40% improvement over the deterministic NAM and GFS simulations for the threat score of the 1 in. $(24 \text{ h})^{-1}$ threshold for the day 1 forecast (Fig. 4a). This improvement was occurring during a period of advances in NWP skill. For example, the GFS 1 in. $(24 \text{ h})^{-1}$ day 1 threat score in 1993 was 0.14, whereas in 2012 it was 0.25. Based on the long-term rate of model improvement, it would take ~13 yr until the GFS attains a day 1 threat score equivalent to the current WPC threat score. This rate is nearly identical to the 14 yr reported by Reynolds (2003) for the 2001 verification year.

The ECMWF precipitation forecast information became available to WPC forecasters in the mid-2000s, and the first full year of formal verification was established in 2008. Verification of the 1 in. $(24 \text{ h})^{-1}$ day 1 forecast over the 2008–12 period shows that the WPC forecast exhibits smaller 5%–15% improvements over the very skillful deterministic ECMWF model (Fig. 4a). However, WPC improvement over the ECMWF model has nearly doubled over the past 5 yr.

A complete picture of precipitation verification must include bias information. In recent years the NAM, GFS, and ECWMF guidance have exhibited a low bias 0.36

0.33

0.30

0.27

0.24

0.21

0.18

0.15

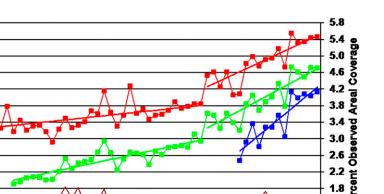
0.12

0.09

0.06

0.03

Threat Score



0.00 1964 1968 1972 1976 1980 1984 1988 1992 1996 2000 2004 2008 2012 Day 1 - Day 2 - Day 3 - Pct Coverage FIG. 3. Time series of annual WPC threat scores for the 1 in. $(24 h)^{-1}$ threshold for the day 1 ed), day 2 (green), and day 3 (blue) forecasts from 1960 to 2012. Percent areal coverage of the in $(24 h)^{-1}$ threshold over the continuous United States over the year is shown by the number

(red), day 2 (green), and day 3 (blue) forecasts from 1960 to 2012. Percent areal coverage of the 1 in. $(24 \text{ h})^{-1}$ threshold over the contiguous United States over the year is shown by the purple line. Linear threat score trends are shown in their forecast day colors. The linear trends are divided into two periods to account for increasing improvement after 1995. (Data are updated yearly online: http://www.WPC.ncep.noaa.gov/images/WPCvrf/WPC10yr.gif.)

at the 1 in. $(24 h)^{-1}$ threshold, while the WPC has sustained a more favorable bias near 1.0 (Fig. 4a). Contemporary verification using the bias-removed threat score shows that WPC has maintained a statistically significant advantage over the ECMWF and GFS during 2011 and 2012 (Fig. 4b). However, the ensemble-based postprocessed QPF from the ENSBC was very competitive. In fact, the ENSBC and WPC forecasts were statistically similar for the 1 in. $(24 h)^{-1}$ threshold during 2012 (Fig. 4b).

Mass (2003) and McCarthy et al. (2007) have asserted that the human is most effective for the near-term forecast. However, the WPC percent improvement over the GFS at the 1 in. $(24 h)^{-1}$ threshold for the day 3 forecast is similar to the percent improvement for this threshold for the day 1 forecast (cf. Figs. 4b and 4d). All guidance, including WPC, has a slight low bias at the day 3 forecast (Figs. 4c,d). For both the day 1 and day 3 forecasts, the competitive skill of the ECWMF forecast is evident, for which the human adds small, but statistically significant, positive skill. However, once again, the WPC is statistically similar to the ENSBC at the 1 in. $(24 \text{ h})^{-1}$ threshold for the day 3 period during 2012 (Fig. 4d). Thus, at least for precipitation at this threshold, the quality added by the forecaster does not appear dependent on forecast projection.

Mass (2003), Bosart (2003), Stuart et al. (2006), and McCarthy et al. (2007) have suggested that the human forecaster may be most adept at improving over NWP guidance for high-impact events. The threat score for the 3 in. $(76.2 \text{ mm}) (24 \text{ h})^{-1}$ threshold is arbitrarily used here as a proxy for a high-impact event. The skill of both model and human forecasts at the 3 in. $(24 \text{ h})^{-1}$ threshold is rather poor when compared to the 1-in threshold, illustrating the challenge of forecasting extreme rainfall events (Fritsch and Carbone 2004; SRNBR). However, the day 1 WPC threat score exhibits a large improvement over select models (Fig. 5a), with a slight dry bias. Contemporary verification accounting for bias shows WPC significantly improved over the GFS in 2012 and ECMWF in both 2011 and 2012 at this threshold. However, once again, WPC was similar in skill to the ENSBC product (Fig. 5b).

1.4

Skill comparisons for the 3 in. $(24 h)^{-1}$ threshold at the day 3 lead time reveal generally less forecaster improvement, with similar model and WPC threat scores (Fig. 5c). In fact, the GFS was superior to the WPC forecast in 2001 and 2003, and the ECMWF was superior to the WPC forecast in 2009. All guidance, except the GFS, is severely underbiased. The authors speculate that the GFS had frequent gridpoint storms (e.g., Giorgi 1991) during the verification period, which may have improved its bias, but degraded its threat score. Contemporary verification shows the WPC bias-removed threat score is not statistically significantly different than the corresponding threat scores from any of the competitive guidance options (Fig. 5d).

All of the above results suggest humans can make statistically significant improvements over competitive deterministic model guidance for precipitation. The

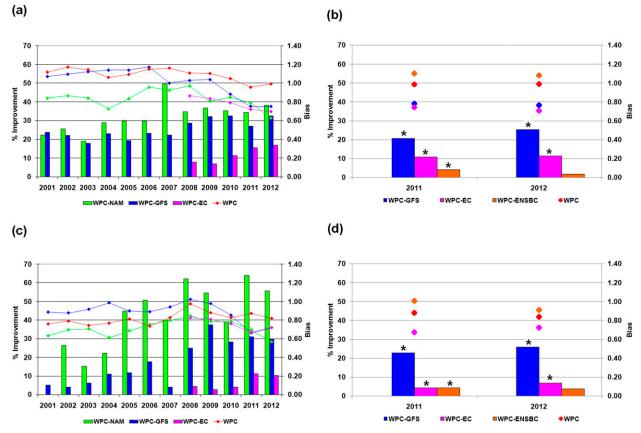


FIG. 4. WPC QPF percent improvement (bars) over the NAM (green), GFS (blue), and ECMWF (purple) for the 24-h accumulated precipitation threat scores on day (a) 1 and (c) 3 for the 1 in. $(24 h)^{-1}$ threshold during the 2001–12 period. The frequency bias for each of the datasets is shown with colored lines having diamond symbols. (b),(d) As in (a),(c), but calculated using bias-removed threat score and including the ENSBC product. Statistically significant differences from WPC at the 90% level are marked by the black asterisk.

magnitude of the quality added by the forecaster is generally not dependent on forecast projection for the 1 in. $(24 \text{ h})^{-1}$ threshold; however, human improvement for extreme rainfall events does appear dependent on forecast projection, favoring larger human improvements over deterministic model guidance in the short-range forecast. However, a downscaled, bias-corrected ensemble forecast available near the same time as the human-modified forecast exhibits similar skill—even for extreme precipitation events.

3. Maximum temperature

a. Production and verification method

WPC forecasters produce a 3–7-day forecast suite including gridded predictions of sensible weather elements to support the National Digital Forecast Database (NDFD; Glahn and Ruth 2003) (Fig. 1b), graphical depictions of the surface fronts and pressure patterns (Fig. 1c), and associated discussion of forecast factors and confidence. Two forecasters work in tandem to complete this task and coordinate with users after assessment of NWP. Since 2004, forecasters have used a graphical interface to apply weights to individual models and ensemble systems to derive a most-likely sensible weather solution. The result of the forecaster's chosen blend can be manually edited.

Before model data are weighted by the forecaster, the data are bias corrected and downscaled to a 5-km horizontal resolution. Bias correction of gridded model data is accomplished using the NCEP decaying averaging bias-correction method of Cui et al. (2012), applied as

$$B_{\text{new}} = (1 - w)B_{\text{past}} + wB_{\text{current}}, \qquad (1)$$

where B_{current} is the latest calculated forecast error given by the difference between the forecast and verifying analysis, B_{past} is the past accumulated bias, and B_{new} is the updated accumulated bias. The NCEP 5-km resolution Real-Time Mesoscale Analysis (RTMA; De Pondeca et al. 2011) was used as the verifying analysis.

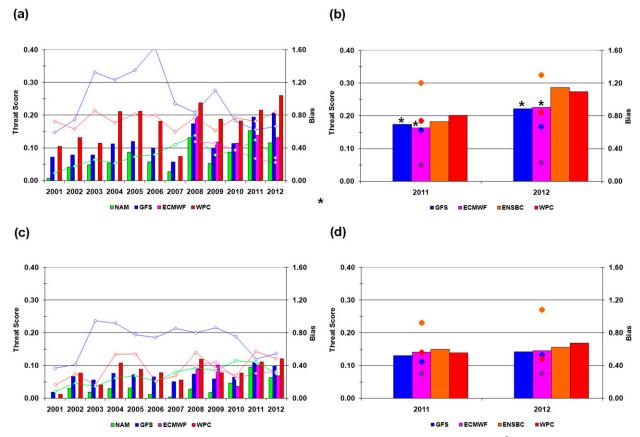


FIG. 5. Comparison of the threat score (bars) and frequency bias (lines with diamonds) for the 3 in. $(24 h)^{-1}$ threshold for day (a) 1 and (c) 3 forecasts during the 2001–12 period. (b),(d) As in (a),(c), but using bias-removed threat score and including the ENSBC product. Statistically significant differences in threat score from WPC at the 90% level are marked by the black asterisks.

The weight factor *w* controls how much influence to give the most recent bias behavior of weather systems. A *w* equal to 2% was used operationally. Once initialized, the bias estimate can be updated by considering just the current forecast error ($B_{current}$) and the stored average bias (B_{past}). The new bias-corrected forecast is generated by subtracting B_{new} from the current forecasts at each lead time and each grid point.

Downscaling of coarse model data onto a 5-km resolution grid is accomplished using a decaying averaged downscaling increment (B. Cui et al. 2013, unpublished manuscript). The downscaling increments are created at each 6-h time step by differencing the coarse 1°-resolution GFS analysis (GDAS) and 5-km resolution RTMA according to

$$D_{\text{new}} = (1 - w)D_{\text{past}} + wD_{\text{current}}, \qquad (2)$$

where D_{current} is the latest calculated downscaling increment given by the difference between GDAS and RTMA, D_{past} is the past accumulated downscale increment, and D_{new} is the updated downscale increment. The weight factor w controls how much influence to give the most recent difference. A w equal to 10% was used operationally. The 6-h grids are then downscaled using the mean downscaling increment for each 6-h period. For maximum and minimum temperatures, at each grid point, the downscaled 6-h grids are compared to each other to find the highest (lowest) values for maximum (minimum) temperature over the 1200–0600 UTC period (0000–1800 UTC period) to get a final maximum (minimum) temperature forecast grid. The verifying maximum (minimum) temperature is taken as the highest (lowest) hourly value from the RTMA at each grid point.

The resulting maximum and minimum temperatures are extracted from the 5-km grid to 448 points for the forecaster to edit where necessary. An objective analysis is performed on the incremental changes made by the forecaster at the 448 points to create a difference grid. The forecaster-edited difference grids are added to the forecaster-weighted output grids to get a final adjusted 5-km forecast grid. Complete details of the methodology for all elements are documented online

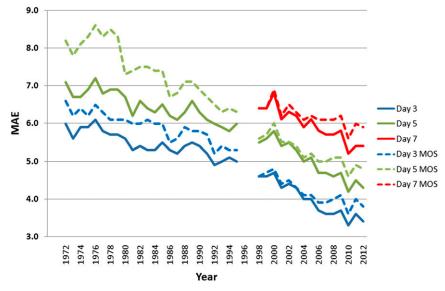


FIG. 6. Time series comparison of the WPC (solid lines) and 0000 UTC GFS MOS (dashed lines) maximum temperature forecast MAE ($^{\circ}$ F) at 98 major stations for day 3 (blue), 5 (green), and 7 (red). Data are missing between 1996 and 1997.

(http://www.wpc.ncep.noaa.gov/5km_grids/medr_5km_ methodology_newparms.pdf).

Both point and gridded verification experiments are conducted. Points are verified by the respective observed station information, while the RTMA is used to verify gridded fields. The fvs (described in appendix B) is used to calculate both point-based and gridded verifications of sensible weather elements, including the determination of statistical significance.

b. Results

Historical verification of maximum temperature at 93 points across the nation shows the marked improvements in medium-range temperature forecast skill over time. Today's 7-day maximum temperature forecast is as accurate as a 3-day forecast in the late 1980s (Fig. 6). Comparison of the 0000 UTC GFS MOS forecast to the 2000 UTC "final" daily issuance of the WPC forecast shows the human forecaster improves upon GFS MOS (Fig. 6). Before 1998 WPC forecasters were verified relative to a version of MOS termed "Kleins" (Klein and Glahn 1974). Starting in 1998, WPC forecasters were verified relative to modern MOS (Glahn et al. 2009), and MOS was used as the starting point for their forecasts. Differences between the Kleins and MOS approaches are apparent, with WPC forecasters improving more against Kleins (Fig. 6). The long-term (30 yr) trend shows the human is improving less over the NWP. However, within the last 7 yr, the WPC forecasts are improving over MOS on the order of 5% (Fig. 6). This improvement may be related to a change in forecast

methodology in 2004, whereby forecasters use a graphical interface to apply weights to individual models and ensemble systems to derive a most likely sensible weather solution. Further, ECMWF guidance became available reliably to forecasters by 2008.

It is necessary to account for the 13-h latency between the WPC final forecast issuance (1900 UTC) and the 0000 UTC GFS MOS (Table 2). WPC issues a preliminary forecast that substantially reduces this latency. A comparison of the preliminary WPC forecast issuance to the 0000 and 1200 UTC MOS is examined. This analysis also uses the full expanded set of 448 points over the conterminous United States (CONUS). The results are summarized as an aggregate of monthly scores averaged during the 2007–12 period (72 months) for maximum temperature. WPC accomplishes a 7%–9% improvement over 0000 UTC MOS with an 8-h latency, as well as a 4%–5% improvement over the 1200 UTC MOS with a human forecast issued 4 h *prior* to MOS (Fig. 7).

TABLE 2. As in Table 1, but for the medium-range forecast guidance from the WPC and GFS.

Guidance source	Time available (UTC)	WPC latency final (preliminary) (h)
WPC final (preliminary)	1900 (1400)	
0000 UTC GFS MOS	0600	13 (8)
0000 UTC ECMWF	0800	11 (6)
0000 UTC ECMWF ensemble	1000	9 (4)
1200 UTC GFS MOS	1800	1 (-4)

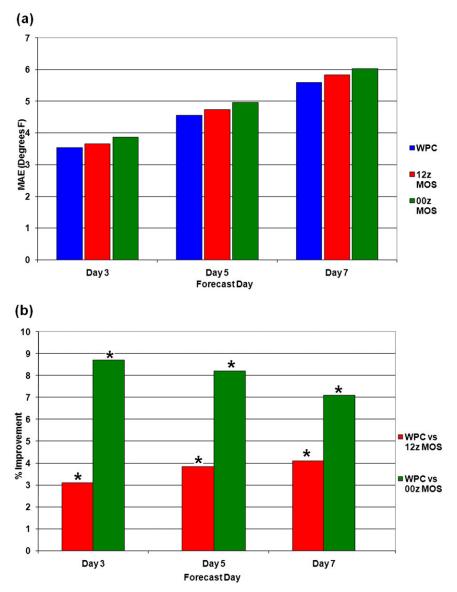


FIG. 7. (a) Comparison of 2007–12 time-averaged maximum temperature MAE for WPC (blue) and 0000 (green) and 1200 (red) UTC GFS MOS for the day 3, 5, and 7 forecast projections. (b) WPC percent improvement over the 0000 (green) and 1200 (red) UTC GFS MOS.

Both results are statistically significant at the 90% level for all days. Using a linear trend over the past decade, it would take \sim 5 additional years for the 1200 UTC GFS MOS to improve to the accuracy of earlier-issued human maximum temperature forecasts.

One hypothesis for the improvement over MOS is that the human forecaster is adept at recognizing when MOS is in large error and, thus, makes large changes from MOS. Figure 8 shows that for frequent small changes the human forecaster makes small improvements over 1200 UTC MOS (\sim 5%). However, for infrequent large deviations from 1200 UTC MOS [i.e., $>8^{\circ}F$ (4.4°C)], forecasters usually make changes in the correct direction, exhibiting average percent improvements near 15%.

Gridded verification allows examination of how the human gridded forecasts compare to downscaled, biascorrected international model guidance and gridded MOS (GMOS; Glahn et al. 2009). The WPC final forecasts are statistically significantly better than all raw downscaled international model guidance and GMOS (Fig. 9a). However, bias-correction substantially improves the maximum temperature model guidance; so much so that the bias-corrected ECMWF ensemble

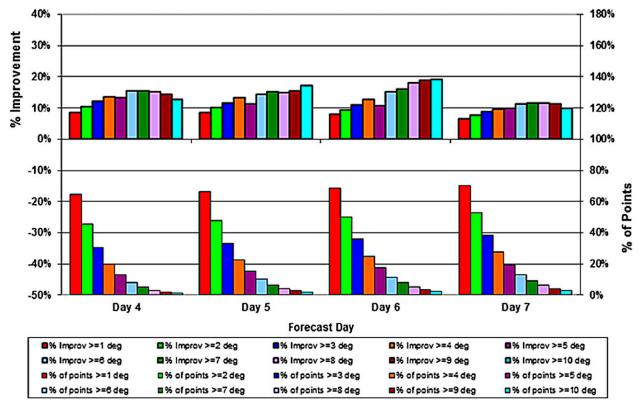


FIG. 8. (top) WPC final forecast percent improvement over the 1200 UTC GFS MOS at stations that were adjusted from MOS during 2012. Percent improvement (left axis) for changes from $\geq 1^{\circ}$ to 10° F (from $\geq -17.2^{\circ}$ to -12.2° C) are displayed for day 4–7-forecasts. (bottom) Corresponding percentage of points adjusted out of a maximum of 448 points (right axis).

mean is statistically significantly superior to the WPC gridded forecast for days 5–7 (Fig. 9b).

Given that surface pressure patterns influence temperature and precipitation patterns, further verification of the WPC mean sea level pressure (PMSL) forecasts for days 3–7 was conducted for 2012. Verification of the anomaly correlation of the deterministic ECMWF and GFS, and their respective ensemble system means, are

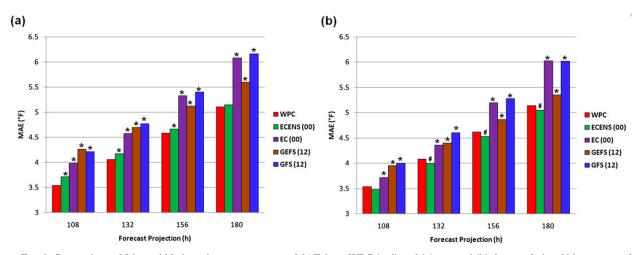


FIG. 9. Comparison of 5-km gridded maximum temperature MAE from WPC (red) and (a) raw and (b) downscaled and bias-corrected 0000 UTC ECMWF (green), ECMWF ensemble (purple), GFS (blue), and GEFS (brown) over the CONUS during 2012. RTMA is used as the verifying analysis. Because of missing data, a homogeneous sample of 321 days is used in (a) and 313 days in (b). Statistically significantly larger (smaller) errors than WPC at the 90% level are shown as asterisks (hashtags).

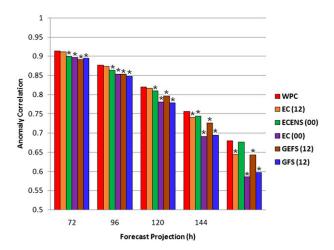


FIG. 10. Comparison of the PMSL forecast anomaly correlation for the WPC final forecast (red) and various international model guidance options: ECMWF (orange), ECMWF ensemble (green), GFS (blue), and GEFS (brown). Statistically significant differences from WPC at the 90% level are shown as asterisks.

shown in Fig. 10. WPC has a higher anomaly correlation score than all guidance at all time ranges; however, WPC is only statistically significantly superior to all these gridded datasets at the day 6 forecast projection. The deterministic ECMWF, which is available near the time of the final WPC forecast issuance, exhibits similar skill to WPC at days 3 and 4. The 0000 UTC ECMWF ensemble mean at day 7 is also similar to the WPC skill.

4. Discussion and summary

Analyses of multiyear verification of short-range precipitation forecasts and medium-range maximum temperature forecasts from the Weather Prediction Center (WPC) are compared to automated NWP guidance. Results show that human-generated forecasts improve over raw deterministic model guidance when verified using both traditional methods as well as contemporary methods. However, perhaps the more compelling result is that on the basis of a statistical analysis of two recent years, human-generated forecasts failed to outperform the most skillful downscaled, bias-corrected ensemble guidance for precipitation and maximum temperature available near the same time as the humanmodified forecasts.

Specifically, historical verification results show that the human-generated WPC QPFs improve upon deterministic raw model guidance, and that the percent improvement has been relatively constant over the past two decades (e.g., Fig. 4a). Medium-range maximum temperature forecasts also exhibit improvement over MOS. The improvement has been increasing during the 2005–12 period. The quality added by humans for forecasts of high-impact events varies by element and forecast projection, with generally large improvements when the forecaster makes changes $\geq 8^{\circ}$ F (4.4°C) to MOS temperatures in the medium-range forecast. Human improvement for extreme rainfall events [3 in. (24 h)⁻¹] is dependent on forecast projection, favoring larger human improvements in the short-range forecast. Contemporary verification confirms that the human forecaster makes small, but statistically significant improvements over competitive deterministic model guidance for precipitation and maximum temperature.

However, human-generated forecasts failed to outperform the most skillful downscaled, bias-corrected ensemble guidance for precipitation and maximum temperature available near the same time as the humanmodified forecasts. Such downscaled, bias-corrected ensemble guidance represents the most skillful operational benchmark. Thus, it is premature to claim superiority by the human forecaster until such forecasts are statistically significantly better than the most skillful guidance. In fact, these results raise the question of whether human-generated forecast superiority has ended.

Indeed, as computer resources advance, models will explicitly simulate more processes, and more and better observations will be used by improved data assimilation systems. These advances will lead to improved NWP guidance. Additionally, more sophisticated postprocessing of raw model guidance, including bias correction and downscaling, will improve automated forecasts of sensible weather elements. Roebber et al. (2004) cite the human ability to interpret and evaluate information as an inherent advantage over algorithmic automated processes. However, artificial intelligence algorithms continue to strive to simulate such human decisions, for example, developing methods to automate selective consensus of ensemble members (e.g., Etherton 2007), or applying artificial neural network and evolutionary programming approaches that "learn" through time (e.g., Bakhshaii and Stull 2009; Roebber 2010). Given this future environment, it is difficult to envision the human forecaster adding quality in terms of forecast accuracy.

On the other hand, there is a distinction between longterm statistical verification (the primary focus of this paper) and critical deviations from skillful guidance in local regions and cases. Contemporary postprocessing approaches are best at correcting repeatable, systematic errors but struggle when the forecast sample size is small for unusual weather scenarios. The forecaster's decision to deviate from skillful automated guidance in these unusual weather scenarios often comes with substantial societal consequences, such as whether a snowstorm will affect a city (Bosart 2003) or whether a killing freeze will occur. Thus, it is especially critical that the forecaster make the very best decision in these scenarios. Figure 8 shows that when forecasters make large changes from MOS, the deviations are generally in the correct direction, providing evidence of skill in recognizing opportunities to deviate from MOS temperatures. Obviously, more evidence of this skill for other variables, benchmarked against more skillful datasets, and filtered to examine only the most critical weather scenarios, is needed to more conclusively demonstrate the forecaster's skill at these deviations.

Bosart (2003) contends that as more and more automation occurs, forecasters' skill at recognizing critical opportunities to deviate from guidance may atrophy. Thus, a key component of assuring the forecaster continues to add quality to NWP is keeping the forecaster engaged in the forecast process. Indeed, the WPC forecasters appear to have learned how to improve over the ECWMF precipitation forecasts over the past 5 yr (Figs. 4a,c), perhaps learning when to deviate from the skillful guidance. From the authors' experience a key to this improvement is greater emphasis on using the most skillful datasets as the forecaster's starting point, and encouraging changes only when confidence is high. Further, improvement can be gained with greater availability of near-real-time verification, using the most skillful guidance as the benchmark. Finally, investment in training forecasters in the strengths and weaknesses of the most skillful guidance, and providing tools to guide forecaster modifications may lead to further forecaster improvements. An example of such a tool is ensemble sensitivity analysis, which can indicate the source of upstream uncertainties for a given forecast parameter. As demonstrated by Zheng et al. (2013), in theory, this tool allows forecasters to identify and monitor the sensitive areas using available observations (satellite, aircraft, or other types) in real time to assess the likelihood of future scenarios.

Emphasis on the most skillful downscaled, biascorrected guidance with supporting near-real-time verification, forecaster training, and tools to guide forecaster interventions has only recently been established at WPC, but has already resulted in forecasters making highorder forecast decisions. These high-order decisions include the removal of outlier forecast guidance that degrades the consensus forecast (e.g., a spurious tropical cyclone), adjusting for regime-dependent biases that are not corrected (or that are introduced) in the postprocessing, and perhaps most importantly, deciding when to substantially deviate from the skillful guidance. Thus, as additional downscaled and bias-corrected sensible weather element guidance becomes operationally available, and with the support of near-real-time verification, forecaster training, and tools to guide forecaster interventions, a key test is whether forecasters can learn to make statistically significant improvements over the most skillful of these guidance options. Such a test can inform to what degree, and just how quickly, the role of the forecaster changes.

Given that only one component of the forecaster's role (accuracy) was considered and only deterministic short-range QPF and medium-range maximum temperature forecasts were assessed, the above results must not be overgeneralized. Downscaling and bias correcting of a full suite of sensible weather elements is not an operational reality yet, as challenges remain with elements such as wind, sky cover, ceiling, and visibility, to name a few. Additionally, the contemporary verification was limited to 2 yr. Further, the financial cost-benefit of human involvement in the forecast process was not considered in the above analysis. Finally, a critical question facing the forecasting community is if and how a forecaster may add quality to the ensemble guidance of many variables (e.g., Roebber et al. 2004; Novak et al. 2008). Thus, a more complete investigation of the human's role in improving upon NWP using other metrics, elements, time ranges, and formats (probabilistic) is encouraged, and may lead to new paradigms for human involvement in the forecast process.

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APPENDIX A

Description of Pseudo-Bias-Corrected Ensemble QPF

The pseudo-bias-corrected ensemble QPF (ENSBC) is a series of 6-h accumulations posted at 6-h intervals. Each 6-h QPF is computed in three phases:

- 1) calculate the weighted ensemble mean (WEM),
- 2) perform the pseudo-bias correction (PBC), and
- 3) apply downscaling based on data obtained from the PRISM precipitation climatology.

The first phase assumes that the larger the uncertainty, the smoother the forecast should be, whereas the smaller the uncertainty, the more detailed the forecast should be. Two ensemble means are computed. The highresolution ensemble mean is the mean of an ensemble made up of relatively high-resolution deterministic single model runs (NAM, GFS, and ECMWF). The full ensemble mean is the mean of a high-resolution ensemble consisting of the same deterministic runs along with the GEM and UKMO simulations, and a standard ensemble system (e.g., the NCEP Short-Range Ensemble Forecast or NCEP Global Ensemble Forecast System). The maximum QPF from the high-resolution ensemble is added as an additional member. The members of the high-resolution ensemble are equally weighted in the warm season, but not in the cold season (October-April), and the weights are adjusted periodically with reference to verification. The members of the full ensemble are equally weighted. The spread of the full ensemble is obtained to compute a normalized spread, $\hat{\sigma}$, which is the full ensemble spread divided by the full ensemble mean, with a small amount added to prevent division by zero. A weight value w is computed at each grid point:

$$w = \frac{\hat{\sigma}}{\hat{\sigma}_{\max}},$$
 (A1)

where $\hat{\sigma}_{max}$ is the domain maximum of the normalized spread. Then, the WEM is computed at each grid point:

$$WEM = w\mu + (1 - w)\mu_{hr}, \qquad (A2)$$

where μ is the full ensemble mean and μ_{hr} is the highresolution ensemble mean. Thus, where the forecast uncertainty as measured by the normalized spread is relatively large, the WEM is weighted toward the full ensemble mean; whereas, at points with lower normalized spread and less uncertainty, the WEM is weighted toward the high-resolution ensemble mean.

In the next phase, the WEM is passed to the PBC, which has nine tuning parameters, is perpetually evolving, and undergoes fairly regular (about every 6 weeks or so) adjustments based on verification. Here, the PBC is described in general terms.

For WEM 6-h precipitation amounts less than about 6–9 mm, the PBC algorithm uses the 10th percentile QPF from the full ensemble to reduce the frequency bias (areal coverage). A weighting function ω is applied to modify the WEM according to

$$WEM = \omega \times WEM + (1 - \omega)QPF_{10}, \qquad (A3)$$

where QPF_{10} is the 10th percentile QPF from the multimodel ensemble. The weighting function linearly increases to one as WEM values increase from 0 up to 6-9 mm, with higher limits for longer forecast projections.

For WEM precipitation amounts greater than ~ 10 mm, the WEM is compared to the high-resolution ensemble mean, which is assumed to have better bias characteristics than the WEM based on the findings of Ebert (2001). The algorithm iterates over an arbitrary list of increasing precipitation thresholds, computes the bias of the volume of QPF exceeding the threshold for the WEM relative to the high-resolution ensemble mean over the entire domain, and then applies a correction factor to bring this volumetric bias to unity for QPF exceeding the threshold. The correction factor is constrained to range between 0.5 and 2.0. As the threshold value increases, the high-resolution ensemble mean is nudged toward the 90th percentile amount from the full ensemble. This is intended to augment bias for higher thresholds, at which ensemble means tend to be underbiased. The successive bias corrections alter the amount of precipitation but not its placement.

The final phase is a downscaling based on PRISM and accomplished using correction factors that vary monthly. Although more sophisticated downscaling techniques exist (Voisin et al. 2010), they are too complex and computationally demanding for the development and computing resources available to the WPC. This simple terrain correction is based on 5-km PRISM data over the western third of the CONUS and 10-km resolution data elsewhere. The method has some similarity to the terrain correction scaling used in Mountain Mapper (Henkel and Peterson 1996). The PRISM data are first remapped to the 32-km WPC QPF grid, preserving area averages. These values are then placed back on the highresolution PRISM grid via bilinear interpolation. Then, the ratios of the original PRISM data to the backinterpolated data are computed. Finally, the ratios are moved to the 32-km resolution by assigning the nearestneighboring value from the high-resolution grid. A monthly varying lower bound ranging from 0.3 in the cold season to 0.9 in the warm season is imposed on the ratios. The downscaling coefficients are replaced with values smoothed using a nine-point smoother at points where the values are less than 1. Multiplication of the pseudo-bias-corrected QPF by the downscaling factor completes the ENSBC processing.

As various model data sources become available, the ENSBC is executed 10 times per day to provide guidance for WPC forecast operations. However, a special configuration of ENSBC execution is performed to create a competitive, realistic benchmark for the WPC QPF suite of day 1–3 forecasts. This configuration releases products in the same order as the WPC manual forecasts for two "final" cycles per day: 0000 and 1200 UTC. The execution schedule permits the creation of products using the same models available to WPC forecasters, but without the human time handicap; therefore, the automated product suite is about an hour earlier than the WPC official delivery deadline for day 1, almost 2 h earlier for day 2, and nearly 4 h earlier for the day 3 forecasts. It should be noted that WPC forecasters often send products well in advance of the deadlines, especially for day 3. All comparisons to ENSBC in the main text are against this benchmark.

APPENDIX B

A Description of the WPC–Environmental Modeling Center (EMC) Forecast Verification System (fvs)

The fvs performs three functions:

- retrieve and combine data records read from one or more Verification Statistics DataBase (VSDB) text files under the control of user-defined search conditions,
- 2) compute performance metrics from the combined data, and
- display the performance metrics and optional statistical significance box-and-whiskers elements graphically or in a text formatted output.

The VSDB records in the text files are created by comparisons of forecast objects to observed objects. This comparison is typically, but not necessarily, a forecast grid to analysis grid, a forecast grid to observation points, or point forecasts to point observations. The software systems used to generate VSDB record files are quite varied and not part of fvs. A single VSDB record usually contains summary statistics for comparisons at multiple analysis or observation points over an area or spatial volume. The summary statistics are either means or fractions. For example, for verification of standardized anomalies, the following means along with the data count are written in the VSDB record: means of forecast and observed anomalies, means of squares of forecast and observed anomalies, and the mean of the product of forecast and observed anomalies. With the data count, these means can be converted into partial sums that are combined in step 1 outlined above. Another example applies to the verification of dichotomous events such as QPF exceeding a specific threshold for which a 2×2 contingency table is required. In this case, each VSDB record contains fractions of forecasts exceeding the threshold, observations exceeding the threshold, and both exceeding the threshold (hits). Again, multiplication by the data count turns these fractions into values that can be added in combining the data according to user-specified search conditions.

In addition to the data values, each VSDB record contains information identifying the forecast source, forecast hour, valid time, verification area or volume, verifying analysis, parameter, and the statistic type. The statistic type is important because it determines what set of performance metrics can be computed once the VSDB records have been retrieved and combined. The user-defined search conditions are important because they inform the fvs as to the independent variable associated with the display of the performance metrics. Any of the identifier fields or combinations of them may be specified as the independent variable; so, the fvs will search for and combine VSDB records as a function of different values (string or numeric) for selected identifier information. The fvs will also perform consistency checks (event equalization) under user direction to assure equal comparisons of multiple forecast sources. If consistency checking is in force, the fvs saves the uncombined data from the search of VSDB records in a binary file. The uncombined data are used in random resampling following the method of Hamill (1999) if the user requests displays of box-and-whiskers objects to depict the statistical significance of differences of any performance metric for paired comparisons of different forecast sources.

Once step 1 is finished, the resulting data may be used to compute a variety of performance metrics, depending on the statistic type. The fvs performs steps 2 and 3 seamlessly, first computing the requested metric, then generating the display. If box-and-whiskers objects are requested, the resampling is done separately at each point along the abscissa of the graphical depiction during the display process. Numerous user-specified parameters are provided to allow the user to control the labels; text fonts; bar, line, or marker characteristics; and colors for the objects appearing in the graphical display.

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